

100-1 大葉大學 選課版課綱

基本資訊

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| 課程名稱 | 智慧型汽車之控制設計:TWN iTS-1 | 科目序號 / 代號 | 1374 / EDR5180 |
| 開課系所 | 電機工程學系博士班 | 學制 / 班級 | 研究所博士班1年1班 |
| 任課教師 | 吳幸珍 | 專兼任別 | 專任 |
| 必選修 / 學分數 | 選修 / 3 | 畢業班 / 非畢業班 | 非畢業班 |
| 上課時段 / 地點 | (二)34N / H371 | 授課語言別 | 其他 |

課程簡介

This course is to provide graduate student the systematic design of the automatic driving system embedded in the smart car Taiwan iTs-1. Taiwan iTs-1 is a heterogeneous system including various sensors, core controller, interfacing and mechanisms to carry out automatic driving. A hierarchical-control autonomy structure to achieve integrated longitudinal and lateral control on highway and urban-road environments. Upper-level control analyzes the traffic situation, determines a driving mode and reference signals. Vehicle-body control executes real-time control-signals tracking. Both human intelligence and behaviors are integrated into vehicle-body control. Collision warning and avoidance maneuvers are embedded in this car. Furthermore, passengers' comfort is also considered in design.

課程大綱

- I. Introduction
 - 1. Mastering Simulink
 - 2. Introduction to CarSim
 - 3. Vehicle Dynamics Simulation using CarSim
- Scene Setup
 - Scene Setup
- 4. Introduction to Automatic Driving System
- II. Autonomous Driving System
 - 5. Vehicle Overview
 - 6. Lane-keeping Design
 - ? Vision-based system
 - ? DSP-based system
 - 7. Lane-changing Design
 - 8. Car-following Design
 - ? ICC mode
 - ? ACC mode
 - ? Platoon mode
 - ? Stop-and-Go
 - . Driving Assistance System
 - 9. Collision Warning/Avoidance Maneuver

10. Comfort Estimation

11. Integrated Lateral and Longitudinal Controller

Final Examination (CarSim Demo)

基本能力或先修課程

no