## 99-1 Preliminary Syllabus, Da-Yeh Univ

Information			
Title	高等動力學	Serial No. / ID	1571 / MUR5003
Dept.	機械與自動化工程學系碩士班	School System / Class	研究所碩士班1年1班
Lecturer	鄭鴻儀	Full or Part-time	專任
Required / Credit	Optinal / 3	Graduate Class	No
Time / Place	(—)A / H455 ( <u></u> )AB / H455	Language	Chinese

## Introduction

Advanced dynamics is to research the Generalized Coordinates, Constraints, Virtual Displacements and Virtual Work, Generalized Forces, Principles of Virtual Work for Static Equilibrium, D 'Alembert 's Principle, Hamilton 's Principles, Lagrange 's Equations. In the class basic theorem of the particles and rigid body will be researched. This course has the goal to cover

- 1. Provide basic principles and relative motion of particles in moving coordinates.
- 2. Provide a research of analytical mechanics about basic concepts and advanced concepts of particles.
- 3. Provide some understanding of the geometry, kinematics, and dynamics of the rigid body.
- 4. To be familiar with the application of dynamics of rigid bodies for advanced concepts.

## **Outline**

1. Basic Principles

**Newtonian Particle Mechanics** 

Coordinates

- a. Rectilinear (Cartesian) Coordinates
- b. Curvilinear Coordinates(Cylindrical, Spherical, Mixed)

Work and Engery

- 2. Relative Motion
- 3. Analytical Mechanics: Basic Concepts

**Generalized Coordinates** 

Constraints

Virtual Displacements and Virtual Work

**Generalized Forces** 

Principles of Virtual Work for Static Equilibrium

D' Alembert's Principle

Hamilton 's Principles

Lagrange 's Equations

- 4. Analytical Mechanics: Additional Topics
- 5. Rigid Body Geometry
- 6. Rigid Body Kinematics
- 7. Rigid Body Dynamics: Basic Concepts
- 8. Dynamics of Rigid Bodies: Advanced Concepts

9. Qualitative Analysis of Rigid Body Motion

## Prerequisite

Dynamics, Physics