

## 98-2 Preliminary Syllabus, Da-Yeh Univ

Information			
Title	機器人學	Serial No. / ID	2289 / MAV4028
Dept.	機械與自動化工程學系	School System / Class	四技部4年1班
Lecturer	陳照忠	Full or Part-time	專任
Required / Credit	Optinal / 3	Graduate Class	Yes
Time / Place	(四)4 / H341 (五)34 / H341	Language	Chinese

Introduction	
Omitted.	

Outline	
<ol style="list-style-type: none"><li>1. Introduction</li><li>2. Spatial Descriptions and Transformations</li><li>3. Manipulator Kinematics</li><li>4. Inverse Manipulator Kinematics</li><li>5. Jacobians: Velocities and Static Forces</li><li>6. Manipulator Dynamics</li><li>7. Trajectory Generation</li><li>8. Manipulator-Mechanism Design</li></ol>	

Prerequisite	
Omitted.	