

98-2 Preliminary Syllabus, Da-Yeh Univ

Information			
Title	機器人學	Serial No. / ID	0528 / MAI4036
Dept.	機械與自動化工程學系	School System / Class	大學日間部4年5班
Lecturer	陳照忠	Full or Part-time	專任
Required / Credit	Optinal / 3	Graduate Class	Yes
Time / Place	(四)4 / H341 (五)34 / H341	Language	Chinese

Introduction	
Omitted.	

Outline	
<ol style="list-style-type: none">1. Introduction2. Spatial Descriptions and Transformations3. Manipulator Kinematics4. Inverse Manipulator Kinematics5. Jacobians: Velocities and Static Forces6. Manipulator Dynamics7. Trajectory Generation8. Manipulator-Mechanism Design	

Prerequisite	
Omitted.	