

101-2 Preliminary Syllabus, Da-Yeh Univ

Information			
Title	機器人學	Serial No. / ID	1983 / MAV4028
Dept.	機械與自動化工程學系	School System / Class	四技部4年1班
Lecturer	陳照忠	Full or Part-time	專任
Required / Credit	Optinal / 3	Graduate Class	Yes
Time / Place	(二)3 / H441 (四)34 / H441	Language	Chinese

Introduction
Omitted.

Outline
<ol style="list-style-type: none">1. Introduction2. Spatial Descriptions and Transformations3. Manipulator Kinematics4. Inverse Manipulator Kinematics5. Jacobians: Velocities and Static Forces6. Manipulator Dynamics7. Trajectory Generation8. Manipulator-Mechanism Design

Prerequisite
Omitted.